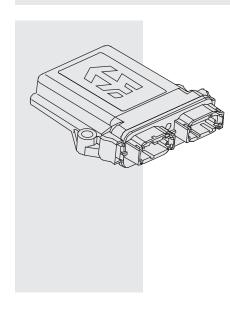
# EVDR5 Five-Valve Driver, Universal Input w/J1939



#### **FEATURES**

- Microprocessor based control (standard software or OEM software on request).
- Standard hardware and software adapts to many applications including interface to a joystick PWM command or proportional signals.
- Independent outputs for four proportional valves (0...2A) and 1on/off valve (< 2 A).</li>
- Interfaces to up to 2 PWM signal inputs (interface to a 2 axis joystick).
- Up to four voltage or current analog inputs: 0-5V, 0-10V, 4-20 mA or 0-20 mA.
- Digital inputs for interface to switches, etc., (up to 6).
- Robust 8...36VDC power supply interface with reverse polarity protection.
- Two, +5V reference voltage to power input devices.
- Thermal overload and overvoltage protection provided.
- Rugged IP67-rated packaging with IP69K-rated plug-in connections.
- Operational from -40 to 85°C (-40 to 185°F).
- CAN for networking capability, user configuration and diagnostics.

#### **DESCRIPTION**

The EVDR5 valve driver provides precise, repeatable control of four proportional solenoid valve coils and one on/off solenoid valve coil. PWM input signals can be from a joystick, a PLC or Engine Control Module. Analog inputs and multiple switched inputs are optional to suit a range of applications. The CAN J1939 communications port, along with the USB-to-CAN adapter, allow the EVDR5 setup parameters to be configured using a PC. Also, the CAN port can be set up to provide communications and control with other devices on the network.

This versatile, multi-function controller is suitable for a wide range of heavy duty industrial, marine, and mobile off-highway equipment applications, such as transmission controls, vehicle traction controls, and drive-by-wire control systems.

#### **RATINGS**

## **POWER REQUIREMENTS:**

Power Required: 8 to 36 VDC

Operating Current: 6 amp maximum load Non-Destructive Voltage: -32 to +36 VDC

#### **SENSOR POWER SUPPLY:**

Two, 5V Sensor Supplies: 50 mA DC each

## **PROCESSING and MEMORY:**

Motorola Microprocessor: MC56F8346

Flash ROM: 128 KByte SRAM: 4 KByte EEPROM: 8 KBytes

All input and output characteristics are configurable with ACP (Application Configuration Programmer).

#### INPUTS:

PWM/Frequency/Digital: 2 inputs

5 to 12 VDC; 0 to 100% DC; 50 Hz to 10 KHz; or Digital Active High/Low Input

Analog/Digital: 4 inputs

0 to 20 mA; 4 to 20 mA with digital inputs active low, 0 to 5V or 0 to 10V with digital inputs active high

#### **OUTPUTS:**

On/Off High Side Driver (2A): 1

PWM Driver, High Side (2A): 4;

PWM Drivers can be configured for On/Off or Proportional

Communications: CAN J1939

### **ENVIRONMENTAL RATINGS:**

Operating Temperature Range: -40 to 85°C (-40 to 185°F)

Storage Temperature Range: -50 to 125°C (-58 to 257°F)

Humidity Tolerance: 115% of nominal system voltage at 90% relative humidity over operating temperature range

Salt Spray Tolerance: 115% of nominal system voltage with 5% salt spray for 48 hours at 35°C (95°F)

Chemical Splash Immunity: Diesel Fuel, engine/machine oil, SAE J1455 chemical agents

Vibration (Shock-isolated components): 7.4 Grms random vibration from 24 Hz to 2 KHz in three orthagonal planes

Moisture Leakage (sealant pressure tolerance): ±0.35 bar (5 psi) against water and water vapor; immersion resistant in 3 ft. (1 meter) of water; meets IP67 standards.

Radiated Immunity: 10 V/M; 80 MHz to 1.0 GHz

Electrostatic Environment: Zero damage during exposure to electrostatic painting process (IEC 61000-4-2)

#### **Materials:**

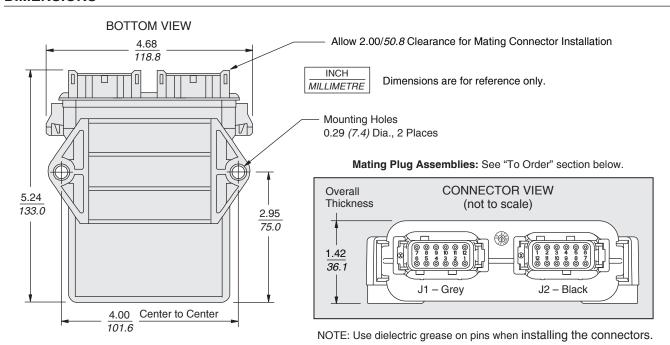
Housing: Thermoplastic with silicone elastomer seals.

Contacts: Tin-plated copper alloy.



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#### **DIMENSIONS**



#### **PINOUT**

### Connector J1 - Grey

Pin	Function
1	Power +
2	Proportional Solenoid 1+
3	Proportional Solenoid 2+
4	Proportional Solenoid 3+
5	Proportional Solenoid 4+
6	Digital Solenoid +
7	Digital Solenoid –
8	Proportional Solenoid 4-
9	Proportional Solenoid 3-
10	Proportional Solenoid 2-
11	Proportional Solenoid 1-
12	Power –

**Pinout Notes:** To ground a PWM input use an analog GND connection pin. Active high digital inputs can be connected to the +5V reference. Active low inputs can be grounded to the analog GND connection pin. Joystick commands X and Y axes affect solenoids depending on how the joystick is wired to the controller. X and Y mentioned here may not correspond to the wiring chosen in a particular application.

### Connector J2 - Black

Pin	Function
1	CAN-H
2	CAN-L
3	Analog In 1 / Digital In 1
4	Analog In 2 / Digital In 2
5	Analog In 3 / Digital In 3
6	Analog In 4 / Digital In 4
7	Analog Ground 2
8	+5V Reference 2
9	Analog Ground 1
10	+5V Reference 1
11	PWM In 1 / Frequency / Digital In 5 (Controls the digital output when analog command type is selected; see notes.)
12	PWM In 2 / Frequency / Digital In 6 (ENABLE control when analog command type is selected; see notes.)

## TO ORDER

Controller Model EVDR5; Part No. 4000249

Connector Kits: J1, DTM06-12A Kit, Grey: 4001976

J2, DTM06-12B Kit, Black: 4001977

Configuration Kit

Includes Converter, Cable and Software: 4000250

CAN Flashing Cable: Part No. 4000695